

# Convexité, robustesse et apprentissage profond pour l'évaluation et la couverture d'options

Vincent Lemaire & Gilles Pagès

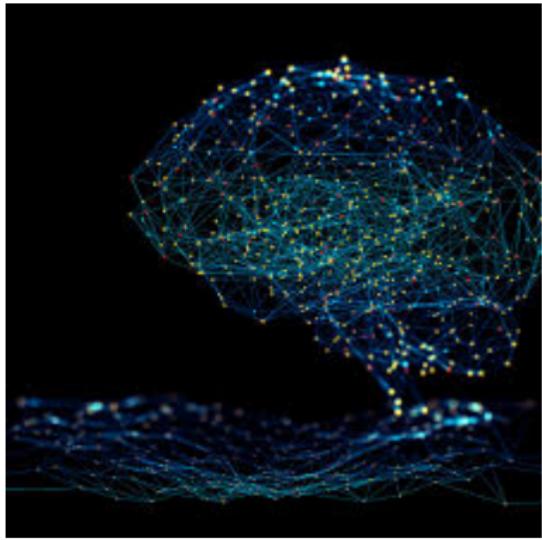
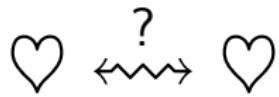
LPSM-Sorbonne-Université

(Labo. Proba., Stat. et Modélisation)



Webinaire Summit Maths-fi & Assurance

17 février 2021



# 1D dynamics of a traded asset

- $(X_t^x)_{t \in [0, T]}$  martingale diffusion representative of the **risk-neutral quotation** of a traded asset.

- Typically, **Black-Scholes model** (1973),

$$X_t^x = x + \int_0^t X_s^x \sigma dW_s \longleftrightarrow X_t^x = x e^{\sigma W_t - \frac{\sigma^2}{2} t}, \quad x > 0, \quad t \in [0, T].$$

- **Local volatility model** [ $\sigma(x) = \vartheta x^{-1/2}$  for CEV model]

$$X_t^x = x + \int_0^t X_s \sigma(X_s^x) dW_s.$$

- **Stochastic volatility model** [Heston  $\vartheta(y) = \sqrt{y}$  (1993)]

$$X_t^x = x + \int_0^t X_s^x \sigma(V_s^\nu) dW_s, \quad V_t^\nu = \nu + \int_0^t (a - \kappa V_s^\nu) ds + \vartheta(V_s^\nu) dB_s, \quad V_0 = \nu$$

with  $\langle W, B \rangle_t = \rho t$ ,  $\rho \in [-1, 1]$ .

- **Loc-Stoch. volatility model** [like SABR model]

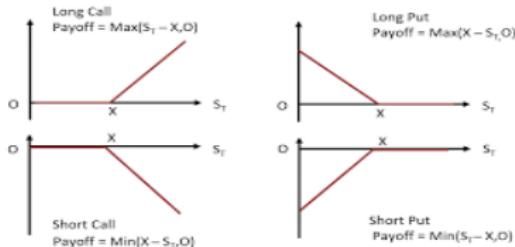
$$X_t^x = x + \int_0^t X_s^x \sigma(X_s^x, V_s^\nu) dW_s + \text{stoch. vol.}$$

# Convex vanilla payoffs

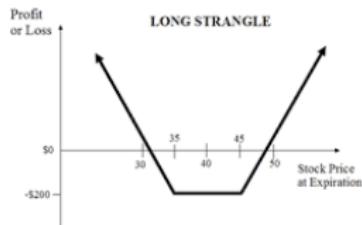
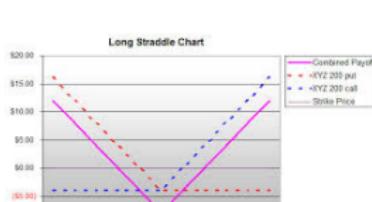
- European option with maturity  $T > 0$  and payoff  $\varphi(X_T^x) \geq 0$  has price and  $\delta$ -hedge given by

$$\mathbb{E} \varphi(X_T^x) \quad \text{and} \quad \partial_x \mathbb{E} \varphi(X_T^x).$$

- Call & Put payoffs (gross profits)

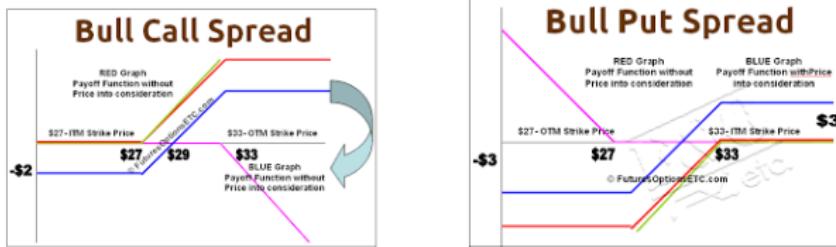


- Straddle & strangle payoffs (gross and net profits)



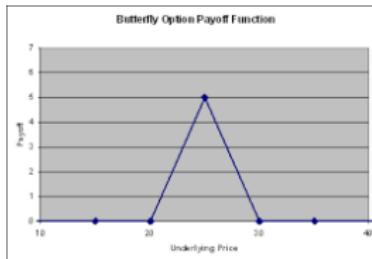
# Non convex payoffs ?

- Call & Put spread payoffs



$$(X_T - K_1)^+ - (X_T - K_2)^+ \quad \& \quad (K_1 - X_T)^+ - (X_T - K_2)^+$$

- Butterfly (difference of two spread options)



$$\varphi(X_T) = (X_T - K_1)^+ - 2(X_T - \frac{K_1 + K_2}{2})^+ + (X_T - K_2)^+$$

- In fact, most payoffs are linear combination of convex payoffs...

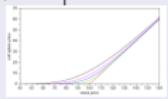
# What does theory say ?

## Theorem (Bergman et al, 1996)

(<sup>a</sup>) For local volatility models for every convex payoff function  $\varphi : \mathbb{R} \rightarrow \mathbb{R}_+$

$x \mapsto \mathbb{E} \varphi(X_T^x)$  is also convex.

(e.g. Black-Scholes Call )



<sup>a</sup>General Properties of Option Prices Y. Z. Bergman, B. D. Grundy and Z. Wiener, *J. of Finance*, 51(5):1573-1610, 1996.

- Intuitive, because of Black-Scholes' world, but not always true !
- Stoch. volatility models: obviously true since by one integration

$$\mathbb{E} \varphi(X_T^x) = \mathbb{E} \hat{E} \varphi \left( x \cdot \exp \left( \int_0^T \sigma(V_s) dW_s - \frac{1}{2} \int_0^T \sigma^2(V_s) ds \right) \right)$$

- But if Loc-Vol and/or  $V_t$  depends on  $X_t$  or multi-asset payoffs (basket, BoC, etc) may fail....

## Theorem (Lemaire-P., 2021)

If a general  $\mathbb{R}^d$ -valued martingale diffusion  $(Y_t^x)_{t \in [0, T]}$  satisfies

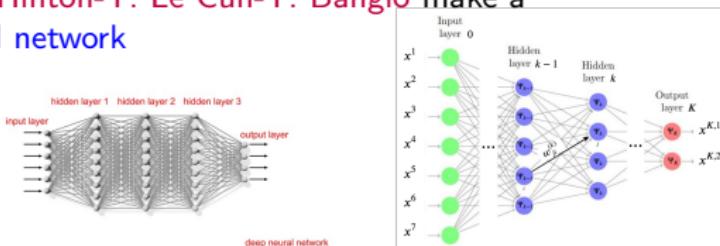
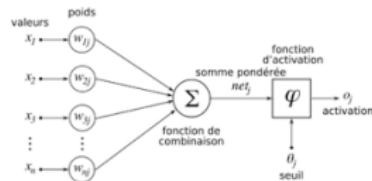
$$dY_t^x = x + \int_0^t \vartheta(Y_s^x) dW_s,$$

with  $W$   $q$ -dim Brownian motion, and  $x \mapsto \vartheta(x)$  is convex for the (matrix partial) order  $A \preccurlyeq B$  if  $BB^* - AA^* \geq 0$  then, for every  $\mathbb{R}_+$ -valued convex functional  $\Phi$ ,

$$x \mapsto \mathbb{E} \Phi(Y^x) \quad \text{is also convex.}$$

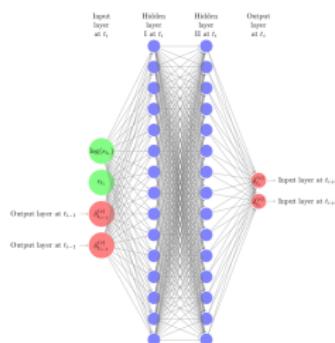
# Deep pricing and $\delta$ -hedging: old and new

- Challenge ImageNet in 2012: G. Hinton-Y. Le Cun-Y. Bengio make a breakthrough with a Deep Neural network

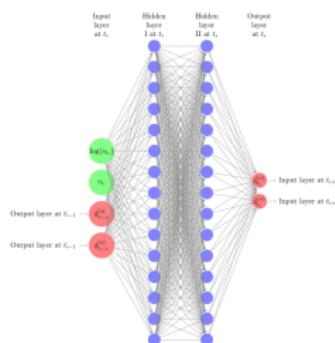


- JPMorgan (Bühler, et al.) et ETH Zürich (J. Teichmann) in 2017 propose Deep Hedging<sup>(1)</sup> to compute (price and) hedge of an option with a neural network.

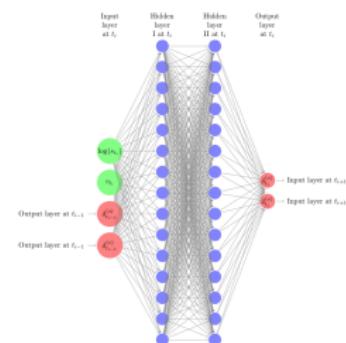
DEEP HEDGING



DEEP HEDGING



DEEP HEDGING



<sup>1</sup>Bühler, H.; Gonon, L.; Teichmann, J.; Wood, B. Deep hedging. *Quant. Finance*, **19**:1271-1291, 2019.

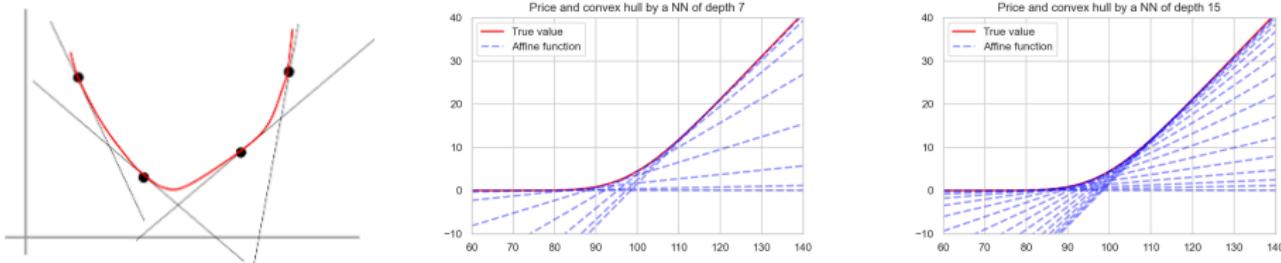
# An alternative approach: ICNN

- (How to) Find an architecture that produces systematically a convex function of the input

$$x \mapsto ICNN(x, \mathbf{w}) \text{ is convex}$$

whatever the hyper-matrix of weights  $\mathbf{w}$  is?

- Input Convex Neural Network



- Starting Idea <sup>(2)</sup> If  $f : \mathbb{R}^d \rightarrow \mathbb{R}$  convex

$$f(x) \left\{ \begin{array}{l} \simeq \max_{k=1:n} [f(x_k) + \langle \nabla f(x_k) | x - x_k \rangle] \\ \geq \end{array} \right.$$

<sup>2</sup>B. Amos, L. Xu, J. Zico Kolter, Input Convex Neural Networks, ICML'17, 2017.

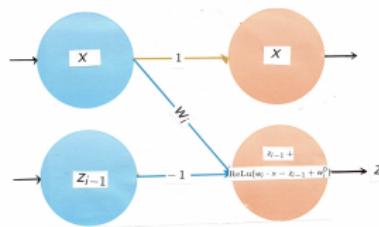
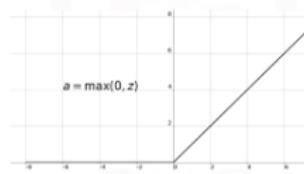
Design an appropriate **neural network** that emulates the convex functions

$$x \mapsto \max_{k=1:n} [\langle w_k, x \rangle + w_k^0], \quad (w_k^0, w_k) \in \mathbb{R}^{d+1}.$$

- **Method 1**<sup>(3)</sup>: change the connectivity of the network  $\Rightarrow$  specific learning script.
- **Method 2**: Set  $z_0 = x$  and set  $z_{i-1}$  output of layer  $i-1$

$$\max(z_{i-1}, \langle w_i \cdot x \rangle + w_i^0) = z_{i-1} + \text{Relu}(\langle w_i \cdot x \rangle - z_{i-1} + w_i^0).$$

ReLU Function



- **Method 2 smooth**: Replace  $\text{Relu}(x) = \max(x, 0)$  (Rectified Linear Unit) by a **convex smooth ( $C^\infty$ ) approximation.**

<sup>3</sup>B. Amos, L. Xu, J. Zico Kolter, Input convex Neural networks, ICML'17, 2017.

# Loss functions

- Suggest to solve the problem(s)
  - On a compact sets e.g.

$$\mathcal{E}_K(f, n) := \min_{(w_k^0, w_k), k=1:n} \left[ \sup_{|x| \leq K} \left| f(x) - \max_{k=1:n} \varphi_k(x) \right| \right].$$

where  $\varphi_k(x) := \langle w_k, x \rangle + w_k^0$  are **affine** functions ( $(w_k^0, w_k) \in \mathbb{R}^{d+1}$ ) or

- On the whole  $\mathbb{R}^d$  with respect to a finite measure  $\mu$  (empirical measure on a (simulated ?) dataset)

$$\mathcal{E}_{r,\mu}(f, n) = \min_{(w_k^0, w_k), k=1:n} \int_{\mathbb{R}^d} \left[ |f(x) - \max_{k=1:n} \varphi_k(x)|^r \right] \mu(dx).$$

with  $r = 1$  or  $r = 2$ .

# Loss functions with penalization

- Suggest to solve the problem(s)
  - On a compact sets e.g.

$$\mathcal{E}_K(f, n, \varepsilon) := \min_{(w_k^0, w_k), k=1:n} \left[ \sup_{|x| \leq K} |f(x) - \max_{k=1:n} \varphi_k(x)| + \frac{1}{\varepsilon} \sum_{k=1}^n (f(x) - \varphi_k(x))^+ \right].$$

where  $\varphi_k(x) := \langle w_k, x \rangle + w_k^0$  are **affine** functions ( $(w_k^0, w_k) \in \mathbb{R}^{d+1}$ ) or

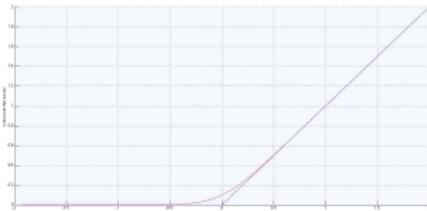
- On the whole  $\mathbb{R}^d$  with respect to a finite measure  $\mu$  (empirical measure on a (simulated ?) dataset)

$$\mathcal{E}_{r,\mu}(f, n, \varepsilon) = \min_{(w_k^0, w_k), k=1:n} \int_{\mathbb{R}^d} \left[ |f(x) - \max_{k=1:n} \varphi_k(x)|^r + \frac{1}{\varepsilon} \sum_{k=1}^n (f(x) - \varphi_k(x))^+ \right] \mu(dx).$$

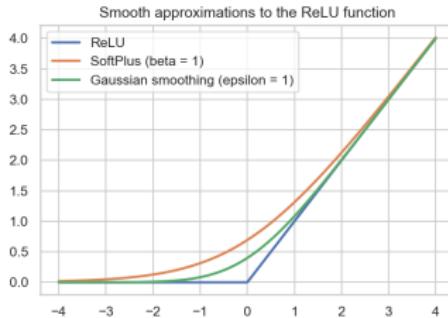
# Probabilistic $\varepsilon$ -smooth Relu

- Let  $\zeta \sim \mathcal{N}(0, 1)$ .

$$\text{Relu}_\varepsilon(x) := \mathbb{E} \text{Relu}(x + \varepsilon \zeta) = x \mathbb{P}(\zeta < \frac{x}{\varepsilon}) + \varepsilon \frac{e^{-\frac{x^2}{2\varepsilon^2}}}{\sqrt{2\pi}}.$$



- Close to soft max (but most likely more adapted to option pricing/hedging)



# Theoretical bounds

- Back to  $w_k = \nabla f(x_k)$  and  $w_k^0 = f(x_k) - \langle \nabla f(x_k), x_k \rangle$ . Appropriate of  $x_1, \dots, x_n$  “guided” by covering numbers and  $L^1(\mu)$ -optimal quantization theory yields

Theorem (Balasz et al. 2015, Lemaire-P.2021)

(a) <sup>a</sup> If  $f : B_{\mathbb{R}^d}(0, K) \rightarrow \mathbb{R}$  is convex and  $\nabla f$  is bounded then

$$\mathcal{E}_K(f, n) = O(n^{-2/d}).$$

(b) If  $f : \mathbb{R}^d \rightarrow \mathbb{R}$  is convex and  $\nabla f$  is Lipschitz and  $\int |\xi|^2 \mu(d\xi) < +\infty$ , then

$$\mathcal{E}_\mu(f, n) = O(n^{-2/d}).$$

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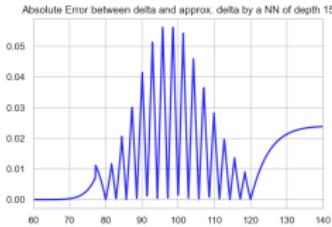
<sup>a</sup>G. Balazs, A. György, C. Szepesvari, Near-optimal max-affine estimators for convex regression, Proc. of the 18th International Conference on Artificial Intelligence and Statistics, PMLR 38:56-64, 2015

# Differentiated network and AAD

- By AAD (Adjoint Automatic Differentiation) applied to the network, one can differentiate the (smoothened) network with respect to its input  $x$ .
- The network provides a good approximation of the price function  $x \mapsto \mathbb{E} \varphi(X_T^x)$ , then the AAD-differentiated network approximates  $\partial_x \mathbb{E} f(X_T^x)$  i.e. the  $\delta$ -hedge at time 0.

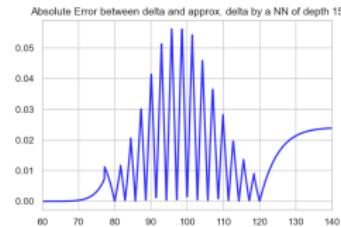
# Preliminary tests

- **Toy model:** Call option with strike  $K = 100$ ,  $x \in [60, 140]$ ,  $\sigma = 0.1$ ,  $T = 1$ .
- **Dataset:** size  $N = 1000$  of  $(x_i, Call(x_i))$  with  $x_i \in [60, 140]$ .
- **Architecture:** ICNN with  $n$  hidden layers and  $d + 1 = 2$  units per layer.
- **Starting state:**  $n = 15$  points  $(x_1, \dots, x_n)$  compute  $\max_{k=1:15} \varphi_k(x)$  (closed form or Monte Carlo).

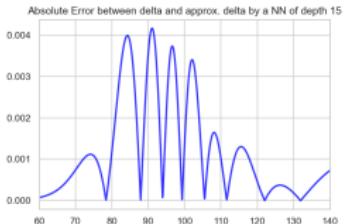
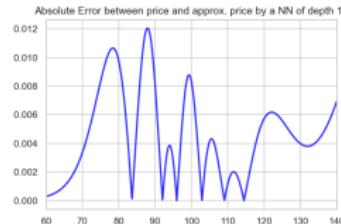
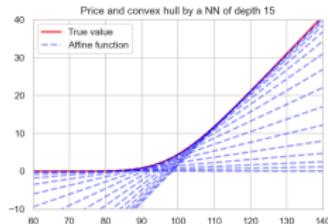


# Preliminary tests

- Starting state:



- After training by 50 epochs of Adam's method with step  $\varepsilon = 10^{-3}$ :



Next step: convex order...

### Theorem (Convex order P., 2016)

If an  $\mathbb{R}^d$ -valued martingale diffusion satisfies

$$dY_t^x = x + \int_0^t \vartheta(Y_s^x) dW_s,$$

with  $W$   $q$ -dim Brownian motion, and  $x \mapsto \vartheta(x)$  is convex for the order  $A \preccurlyeq B$  if  $BB^* - AA^* \geq 0$  and  $\vartheta \preccurlyeq \sigma$  then, for every  $\mathbb{R}_+$ -valued convex functional  $\Phi$  :

$$\mathbb{E} \Phi(Y^{\vartheta,x}) \leq \mathbb{E} \Phi(Y^{\sigma,x}).$$

Merci de votre attention !